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The Hierarchical Structure of the Firm: A Geometric Perspective

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Abstract

This paper incorporates hierarchical structure into the neoclassical theory of the firm. Firms are hierarchical in two respects: the organization of workers in production and the wage structure. The firm’s hierarchy is represented as a sector of a circle, where the radius represents the hierarchy’s height, the width of the sector represents the breadth of the hierarchy at a given height, and the angle of the sector represents span of control. A perfectly competitive firm chooses height and width, as well as capital, in order to maximize profit. We analyze the short run and long run impact of changes in scale economies, input substitutability, and input and output prices on the firm’s hierarchical structure. We find that the firm grows as the specialization of its workers increases or as its output price increases relative to input prices. The effect of changes in scale economies is contingent on the price of output. The model also brings forth an analysis of wage inequality within the firm, which is found to be independent of the firm’s hierarchical organization of workers, and only depends on the firm’s wage schedule.

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1. Introduction

The hierarchical structure of firms exhibits ample variation. Firms in heavy manufacturing industries typically have tall hierarchies (e.g., General Electric). Conversely, firms in the services industry, such as consulting firms, tend to be relatively flat and less hierarchical (e.g., Ernst & Young). What are the economic factors that influence the hierarchical structure of firms? How does the hierarchical structure respond to a change in these factors? How is production related to hierarchical structure?

The neoclassical theory of the firm, as stated in Samuelson (1947), is silent in these respects. Narrowly defined, the neoclassical firm chooses inputs in order to maximize profit, taking prices and technology as given. Labour is usually treated as a homogeneous input, earning a uniform wage inside the firm. This treatment of labour is in great contrast with two stylized facts of firms: (1) firms have fewer workers at higher ranks; and (2) wages rise with the rank of workers within the hierarchy. These observations imply that firm production involves a hierarchical organization of workers, as well as a hierarchical scheme of wages.

This paper incorporates hierarchical structure, in terms of production and wages, into the neoclassical theory of the firm. The extended framework inherits the key features of neoclassical firms whilst providing an analysis of the firm’s hierarchical structure and how this affects the production process. This has the advantage of retaining standard results from the neoclassical framework, whilst developing new insights regarding hierarchical structure, in a parsimonious model. Instead of taking the span of control and number of levels in the hierarchy as exogenous, we specify production directly in terms of these hierarchical attributes.

A novelty of the paper is the use of a geometric approach to pose the optimization problem. More specifically, we model the shape of the hierarchy using a sector of a circle. This allows us to employ the geometric formulae related to the sector of a circle in the construction of the cost function, which keeps the analysis tractable. This geometric approach captures the essential features of the firm’s decision process, within a remarkably simple framework. The firm maximizes profit by choosing capital, the height of the hierarchy, and its width at each level. The height of the hierarchy is given by the radius of the sector. The width is encompassed by the angle of the sector, or ‘span of control’.

The framework sheds new light on the question of the boundaries of the firm and firm size, originally posed by Coase (1937). By solving the firm’s hierarchical structure design
problem, we provide a new characterization of Coase’s original insight, namely, that the firm expands until the marginal benefit of doing so is no longer greater than the marginal cost. A striking feature is that this is obtained without any reference to transaction costs. We distinguish between vertical and horizontal expansion of the firm. In our framework, this corresponds to the decision on the firm’s height, and its width at each hierarchical level.1

In considering the hierarchical structure of the firm, we come across the notion that different levels of the hierarchy command different wage rates. We incorporate this by introducing a wage schedule, which rises convexly with escalation along the hierarchy. This brings forth the question of wage inequality within the firm. The simplicity of the framework allows us to calculate Theil inequality indices (Theil, 1967) and to analyze how wage inequality relates to the structure of the firm. By choosing a plausible parameterization for the wage schedule, we obtain a measure of within firm wage inequality that approximates observed earnings inequality in the United States.

1.1. Related Literature
With prescient insight, Marshall (1898, Book IV, Ch. XIII and 1923, Book II, Chs. X-XII) noted the importance of hierarchical organization for the firm’s production process. More recently, Erich Gutenberg (1951) argues that firm productivity depends on the organization and complementarity of inputs rather than just the potential productivity of each input (Albach et al., 2000). Other authors2 have also pointed out that the organization of workers, when combined with other factors, influences how successful a firm is in achieving its objective. The argument is that characteristics such as teamwork and the monitoring of workers are crucial to the workings of the firm (Alchian and Demsetz, 1972).

Approaches to the hierarchical structure of the firm are diverse. One approach studies the ‘distribution of authority’ within the firm. This approach attempts to explain how workers are organized according to the influence one has over others (Shapley and Palamara, 2000; Rajan and Zingales, 2001; Hu and Shapley, 2003a, 2003b).

Another approach focuses on the ‘shape’ of the firm, and provides insights on its structural design. The shape is determined by the number of levels in the hierarchy and by the span of control of superiors. The models in this branch range from theories of knowledge acquisition and communication flows (Garicano, 2000), information processing (Radner,
1992), promotion tournaments (Lazear and Rosen, 1981; Dubey and Haimanko, 2003), to loss-of-control along the hierarchy, possibly due to imperfect communication (Williamson, 1967) or to imperfect observation and agency problems (Qian, 1994).

Other approaches deal with issues of asset ownership and control (Grossman and Hart, 1986; Hart and Moore, 2005), as well as incentive (agency) problems (Jensen and Meckling, 1976; Mookherjee and Reichelstein, 2001). In Yanes et al. (2005), we introduced a geometric approach to the firm’s hierarchical design problem, focusing on a specific example. The present study presents a more comprehensive treatment of that approach.

1.2. Structure of the Paper
In section 2, the firm’s general problem of hierarchical design is presented, and we show how previous studies have reduced the general case to specific but tractable problems. Section 3 presents a model to solve a stylized version of the general problem. Section 4 offers an illustration using specific functional forms. Section 5 then provides comparative statics results for a particularly simple version of the model. Section 6 discusses wage inequality within the firm. Conclusions are offered in section 7.

2. The General Problem
One can imagine a perfectly competitive firm that designs itself in order to maximise profit. Its design problem is to choose how much labour and non-labour input to use, as well as how to allocate its workers into different ‘positions’. Positions are defined by seniority and type of activity (e.g., accounting, marketing, maintenance, etc.), and each position is filled by one worker. In solving this problem, a perfectly competitive firm takes output and input prices, as well as technology, as given. In particular, the firm takes as given the market-determined wage profile for workers being hired in different positions. On the other hand, the firm determines the span of control of each worker, namely, how many supervisees he or she will be responsible for. This is a difficult problem to solve, which can be stated formally in the following manner. Let:
\[ P = \text{Price of output.} \]
\[ Y = \text{Output.} \]
\[ r = \text{Price of non labour input.} \]
\[ K = \text{Non labour input.} \]
\[ a = 1, \ldots, A \] denotes activity. Not all activities are performed in all hierarchical levels.
\[ h = 1, \ldots, H \] denotes level of seniority, with 1 being the highest.
\[ \theta_{ah} = \text{Number of supervisees for a worker at position } ah. \]
\[ \theta = [\theta_{ah}]_{a,h} \], a matrix listing the supervision structure of the firm; i.e., span of control.
\[ w_{ah} = \text{Market wage rate for a worker specialized in position } ah. \]

The wage rate is typically rising with seniority. That is, \( w_{ah} \) is decreasing in \( h \) and can be interpreted as a pay scale resulting from labour market conditions. The wage will also vary between activities, but for our purposes this does not need to be specified. The firm’s problem is specified as follows:

\[
\begin{align*}
\max_{A, H, R, K} & \quad \pi = PY - \sum_{a=1}^{A} \sum_{h=1}^{H} w_{ah} - rK \quad \text{s.t.} \quad Y \leq F(A, H, \theta, K) \quad Y \geq 0.
\end{align*}
\]

\( F(A, H, \theta, K) \) is the firm’s production technology. If \( F(\cdot) \) is continuous and quasi-concave (strictly or otherwise), then existence of solutions to the firm’s problem is warranted. Moreover, if we impose strict quasi-concavity on \( F(\cdot) \), or strict convexity on \( w(\cdot) \), the solution is unique. The production technology encompasses the details of how workers interact, problems of monitoring, the efficiency of information and communication flows, and so forth.

At this level of generality, the firm is free to choose any organizational form. We can imagine pyramidal firms, with a single top manager. In this case there would be exactly one worker at seniority level 1. Other structures are also possible. We can imagine a corporation which is managed by a board of trustees. In this case, we could have several positions at seniority level 1. Moreover, the organization need not necessarily expand (it may even contract) as we move onto lower levels of seniority, and we can imagine positions which do not have supervisory responsibilities, that is, they have no ‘off-spring’. Furthermore, the optimal organizational structure need not be symmetric\(^3\). The resulting optimal structure will depend on how \( A, H \) and \( \theta \) affect output and costs, and the usual ‘marginal benefit equals marginal cost’ reasoning applies.

---

\(^3\) This framework could also be used to analyse not-for-profit organizations, e.g., charities, or some religious and governmental organizations. In this case profit maximization could be replaced with other objectives, such as output maximization subject to non-negative profits.
Several attempts have been made at solving problems of this type. Each approach makes different simplifying assumptions in order to restore tractability. The closest papers to our work are those by Williamson (1967) and Qian (1994), so we shall show how their frameworks relate to the ‘general problem’ in (1). Both Qian and Williamson assume ‘no working foremen’, that is, the only workers producing physical output are workers at the bottom of the hierarchy. The contribution of higher level workers lies in inducing bottom level workers to produce more, through coordination, monitoring, etc.

Williamson (1967) assumes that the span of control or the number of supervisees ($\theta_{ab}$) is constant across the hierarchy, wages increase with seniority at a constant rate, and output is a Cobb-Douglas production function with the number of workers in each hierarchical layer acting as inputs. In our notation, Williamson’s production function can be written as

$$Y = c \prod_{b=1}^{h-1} \left( A \sum_{a=1}^{b} \theta_{a,h} \right),$$

where $c$ is a constant converting input to output, and $\alpha \in (0,1)$ is a constant measuring loss of control. In this formulation the top manager’s labour input is equal to unity, and bottom level workers do not have any supervisory duties. Control loss is justified by reference to imperfect communication of instructions between layers. With the exception of top management, control loss is present at all levels of the hierarchy, and reduces the productivity of inputs, namely, the number of workers in each hierarchical layer. With a constant span of control, the production function simplifies to

$$Y = c \left( A \theta \right)^{h-1} \quad (c.f., \text{Williamson, 1967, p. 128}).$$

Williamson further assumes that non-labour costs are a constant fraction of output. In this model, the only choice variable is the number of layers in the hierarchy, which is chosen in order to maximize profit. The firm operates under decreasing returns to scale, which arise from the loss-of-control problem.

Qian (1994) further elaborates Williamson’s approach by using optimal control techniques to endogenize, in addition to number of layers in the hierarchy, the span of control, loss of control and the shape of the wage schedule. Loss of control is now justified by reference to misaligned incentives, and the firm solves a principal-agent problem which results in workers receiving efficiency wages. Moreover, Qian allows for non-constant spans of control, effort levels, and rates of increase for wages in the hierarchy. Assuming a fixed capital-labour ratio, Qian specifies production as a recursive technology taking the form

$$y_h = y_{h-1} \alpha_h,$$

where $y_{h-1}$ denotes intermediate output at hierarchical level $h-1$ and $\alpha_h \in [0,1]$ denotes workers’ effort at hierarchical level $h$. Workers’ ability to choose effort is the source of control loss. In our notation, final output can be written as follows:
\[ Y = C \left( \sum_{i=1}^{I} \theta_{i,1} \right) \prod_{h=1}^{H} \alpha_h, \] where \( \sum_{i=1}^{I} \theta_{i,1} \) is the number of bottom level workers—the only ones producing any physical output, \( C \) is a constant denoting potential output per bottom level worker, and \( \prod_{h=1}^{H} \alpha_h \) denotes cumulative effort along the hierarchy. If one assumes that effort levels are constant and that span of control is constant across activities\(^4\), then the production function simplifies to \( Y = CA\theta \alpha^{H-1} \), which is similar to Williamson’s. However, Qian assumes that the number of lowest level workers, \( A\theta \), is a constant, whilst for Williamson this is determined by the span of control once the number of layers is chosen. Like Williamson, Qian finds that production occurs under decreasing returns to scale, again due to loss of control.

This study takes a different route. We abstract from the internal details of the hierarchy such as loss-of-control or information flow problems by introducing a production function that does not depend on the interaction between hierarchical layers. Instead, we take the number of layers and the span of control as the relevant information about the organization of workers. Whence, these attributes are used as direct inputs in production, alongside capital. The two hierarchical structure inputs, like capital, feature diminishing marginal returns. In our formulation, problems such as loss-of-control and information flows (Radner, 1992) are captured by these diminishing marginal returns, and are not modelled explicitly. The span of control is an endogenous variable, and for simplicity, is assumed identical at each level of the hierarchy. Also, instead of considering the wage schedule as being determined inside the firm, we take this as given by the market. This seems plausible for the case of a perfectly competitive firm. To recap, our endogenous variables are: the number of layers in the hierarchy, the span of control, and capital. By endogenizing capital, we obtain interesting results for the capital-labour ratio. This feature further distinguishes the present paper from the work of Williamson (1967) and Qian (1994): Williamson assumes a fixed capital-output ratio, while Qian assumes a fixed capital-labour ratio. As we shall see in the next section, our approach will allow some convenient simplifications of the general problem.

\(^4\) Note that Qian does not assume constant effort levels. On the contrary, in his general model, he finds decreasing effort and wages along the hierarchy.
3. A Geometric Approach
Consider a sector of a circle as an abstract representation of the hierarchical structure of a firm, as depicted in Figure 1. The height of the firm is represented by $H$, and can be interpreted as the number of levels in the hierarchy. The angle, $\theta$, can be interpreted as span of control from any supervisor’s perspective. In the figure, $h$ represents the distance from the highest position of the hierarchy. Thus $h$ is inversely related to seniority, with $h = 0$ representing the top manager and $h = H$ representing the lowest echelon of the hierarchy. $b$ represents the number of workers in a particular hierarchical level, $h$, and it can be interpreted as the width of the firm at that level. Using the arc length formula, we have $b = h\theta$.

![Figure 1. Firm Hierarchy as a Sector of a Circle](image)

With this abstract representation, the problem of designing the hierarchical structure of the firm is reduced to choosing the height ($H$) and the angle ($\theta$) of the sector.\(^5\) Similarly to Williamson (1967) and Qian (1994), our representation does not deal with the question of which activities are performed by which workers. As a result, the wage rate and output do not depend on activities.

In posing the firm’s design problem as one of choosing the dimensions of a geometric sector, we make the assumption that the hierarchy features a continuum of workers, both horizontally and vertically. Thus, the area of the sector, given by $\theta H^2/2$, represents the firm’s workforce. The firm’s profit is specified as follows:

$$\pi = PY - \int_0^H b(h, \theta)w(h)dh - rK,$$

(2)

\(^5\) More generally, one could allow the span of control to differ according to the hierarchical level. This would generate a more complicated geometrical structure, and the sides of the sector would no longer be straight but would bend outwards for increases in the span of control, or inwards for span of control reductions.
where $P$ is output price, $Y$ is output, $r$ is the rental rate of capital, $K$ is capital input, 
$b(h, \theta) = h \theta$ is the width of the hierarchy at level $h$, and $w(h)$ is the wage schedule. The wage schedule is a differentiable, convex and decreasing function of $h$: $w_h(h) < 0, w_{hh}(h) > 0$, where subscripts denote first and second derivatives, respectively. We assume that this wage schedule is set by the market. The firm is perfectly competitive, and consequently takes prices, including the wage schedule, as given.  

Hierarchical structure is incorporated directly into the firm’s production function, allowing an inspection of the forces that affect hierarchical structure and production. The major departure of our model from the standard neoclassical model of the firm is that the labour input is measured in terms of $H$ and $\theta$, which enter the production function in the following manner: $Y = F(H, \theta, K)$. Since costs are strictly convex, all that is required for existence and uniqueness of the solution to the firm’s profit maximization problem is that the production function be continuous and strictly quasiconcave (for existence, but not necessarily uniqueness, continuity and non-strict quasiconcavity are sufficient). In addition, it will be convenient to assume that $F(.)$ is twice continuously differentiable ($C^2$), and features diminishing marginal returns. Diminishing marginal returns to $H$ and $\theta$ reflects the ‘loss-of-control’ the top manager faces in the trade-off between height (distance to supervisees) and width (span of control) of the hierarchy (Qian, 1994).

In the short run, capital is fixed and we introduce the following inequality constraint: $K \leq \overline{K}$. If we further assume that $F(.)$ is increasing in its arguments, this constraint will be binding. In this case, first order conditions for the firm’s optimization problem are given by:

$$
PF_{\theta}(H^*, \theta^*, \overline{K}) = \int_0^{H^*} hw(h) dh,
$$

$$
PF_{H}(H^*, \theta^*, \overline{K}) = \theta^* H^* w(H^*).
$$

If $F(.)$ is strictly quasiconcave and $C^2$, these yield unique solutions of the generic form $\theta^*(P, \overline{K})$ and $H^*(P, \overline{K})$. The interpretation of (3) is straightforward; the left hand sides are

---

6 An interesting extension would be to endogenize the construction of the wage schedule. Qian (1994) obtains a convex and decreasing schedule based on the notion of imperfect observability of subordinates’ effort. To ameliorate the agency problem, Qian introduces efficiency wages and obtains a wage schedule which decreases along the hierarchy. An alternative route would be to consider the demand and supply sides of the labour market, together with some notion of differentiation in the labour input (perhaps drawing on differences in human capital). This extension lies outside the scope of this study, and its consideration is deferred for future work.
the marginal benefits from a marginal change in $\theta$ or $H$, respectively, and the right hand sides are the marginal costs.

In the long run, capital is flexible and an additional first order condition needs to be considered:

$$PF_x\left(H^{\prime\prime}, \theta^{\prime\prime}, K^{\prime\prime}\right) = r. \quad (4)$$

Replacing $K$ with $K^{\prime\prime}$ in (3), equations (3)-(4) yield unique solutions of the following generic form $^7$: $\theta^{\prime\prime}(P,r), H^{\prime\prime}(P,r), \text{ and } K^{\prime\prime}(P,r)$. Note that these factor demands do not depend on wages. This is due to the fact that the wage schedule, $w(h)$, is determined once the height of the hierarchy, $H$, has been chosen.

4. An Illustrative Example

In this section we assume a specific functional form for the production function, $F(H, \theta, K)$:

$$Y = K^\alpha \left( H^\rho + \theta^\rho \right)^{\beta/\rho}, \quad (5)$$

with $\rho < 1$, $\rho \neq 0$, $\alpha, \beta > 0$. This implies that output depends not only on capital and labour, but also on how the firm’s workforce is organized. Whereas the firm’s (unorganized) workforce is equal to the area of the sector, given by $\theta H^2/2$, its ‘effective’ (organized) labour is given by $(H^\rho + \theta^\rho)^{\beta/\rho}$.

4.1. Returns to Scale

If both $\theta$ and $H$ change by factor $s^{1/3}$, $s \in \mathbb{R}_+$, the firm’s workforce becomes $s\theta H^2/2$, while effective labour changes to $s^{\beta/3}(H^\rho + \theta^\rho)^{\beta/\rho}$. Thus, $\beta/3$ measures returns to scale in the formation of effective labour, where:

$$\beta/3 \begin{cases} <1 & \text{: decreasing returns to scale} \\ =1 & \text{: constant returns to scale} \\ >1 & \text{: increasing returns to scale} \end{cases} \quad (6)$$

To examine returns to scale in production of output, both the workforce and capital must change by the same proportion, $s$. This is achieved by multiplying $H$ and $\theta$ by $s^{1/3}$ and $K$ by

---

$^7$ At this level of generality it is difficult to derive interesting comparative statics results, and in subsequent sections we shall make some simplifying assumptions to this end. The general results are available from the authors.
s, yielding a new output of \( s^{\alpha+\beta/3} F(H, \theta, K) \), where \( F(.) \) is as defined in (5). Thus, \( \alpha + \beta /3 \) measures returns to scale in production of output, where:

\[
\alpha + \beta /3 \begin{cases} 
< 1 & \text{: decreasing returns to scale} \\
= 1 & \text{: constant returns to scale} \\
> 1 & \text{: increasing returns to scale}
\end{cases}
\] (7)

4.2. The Elasticity of Substitution and Intra-firm Specialization

In (5), the elasticity of substitution between \( H \) and \( \theta \) is given by \( 1/(1-\rho) \). If workers at different levels perform different tasks, then an increase in \( \rho \) indicates a decrease in the task specialization of workers within the firm. In other words, there is a decrease in intra-firm specialization. An indicator of intra-firm specialization is whether subordinates are able to fill their superior’s role in case of absence, and vice versa. For example, intra-firm specialization is expected to be higher in the manufacturing sector, relative to the fast food catering sector. In a fast food shop, a manager can easily take up the task of cooking in the absence of some workers. On the contrary, in a manufacturing factory, a manager may not be able to perform the task of a technician. In particular, as \( H \) and \( \theta \) become more substitutable, the firm would be more inclined to give up one superior for another lower-level worker in order to reduce total labour cost.

4.3. Wage Structure

The wage schedule is determined by the market. It is uniform across each level and increases convexly as we move up the hierarchy. Total wage payments to workers at level \( h \) for a given \( \theta \) are equal to \( b(h, \theta)w(h) \). Total wage payments for the firm are given by the integral of \( b(h, \theta)w(h) \) from \( h = 0 \) (the top manager) to \( h = H \) (the lowest level worker). For tractability, the wage schedule is specified as follows:

\[
w = \frac{W}{H^{\phi}},
\] (8)

where \( \phi \) is (the absolute value of) the wage elasticity with respect to \( h \), and \( W \) is a constant which can be interpreted as the economy wide average wage rate at hierarchical level \( h = 1 \). It is worth noting that since the tip of the hierarchy is normalized at \( h = 0 \), vertical expansion
of the firm will always be in the downward direction. To see this, note that the wage schedule is downward sloping in \( h \), and cost per worker declines as the hierarchy expands vertically.\(^8\)

In the short run, capital is fixed at \( K^* \), thus, we need to consider only the distribution and quantity of labour within the hierarchy. The firm’s problem is to choose \( H \) and \( \theta \) in order to maximize profit. After substituting the functional forms specified in (5) and (8), the optimal values of \( H \) and \( \theta \) solve the system set out in (3). This yields:

\[
\theta^* = \left( \frac{PK^\alpha}{W} \frac{(3-\phi)^{1-\rho}}{(2-\phi)^{\rho}} \right)^{\frac{1}{\beta-\rho}}
\]

(9)

\[
H^* = \left( \frac{PK^\alpha}{W} \frac{(3-\phi)^{1-\rho}}{(2-\phi)^{\rho}} \right)^{\frac{1}{\beta-\rho}}
\]

(10)

To rule out complex values for \( \theta^* \) and \( H^* \), we assume \( \phi < 2 \) in what follows. In the long run, capital is no longer fixed but is chosen by the firm. To obtain the long run solutions, \( \theta^{**} \), \( H^{**} \), and \( K^{**} \); substitute (5) and (8) into (3) and (4), taking care to replace \( K \) with \( K^{**} \) in (3). The solutions are as follows:

\[
\theta^{**} = \left[ \frac{PC^\alpha \beta^{\beta-\alpha}}{r \alpha W \beta^{1-\alpha}} \frac{(3-\phi)^{1-\rho}}{(2-\phi)^{\rho}} \right]^{\frac{1}{(1-\rho)(1-\alpha)-\beta}}
\]

(11)

\[
H^{**} = \left[ \frac{PC^\alpha \beta^{\beta-\alpha}}{r \alpha W \beta^{1-\alpha}} \frac{(3-\phi)^{1-\rho}}{(2-\phi)^{\rho}} \right]^{\frac{1}{(1-\rho)(1-\alpha)-\beta}}
\]

(12)

\[
K^{**} = \left[ \frac{P^{\beta-\phi}}{r^{\beta-\phi}} \frac{(3-\phi)^{1-\rho}}{(2-\phi)^{\rho}} \right]^{\frac{1}{(1-\rho)(1-\alpha)-\beta}}
\]

(13)

We now proceed to make some simplifications in order to analyse these solutions.

---

\(^8\) The perceptive reader may have noticed that this functional form for the wage schedule implies that the top manager receives a wage of infinity. However, this does not pose a problem: with a continuum of workers, the top manager's measure is zero and hence the total wage bill remains finite.
5. Comparative Statics and Further Simplifications

In order to simplify the analysis of the comparative statics properties of the model, we set \( W \) and \( \phi \) to unity. This implies that the wage schedule, (8), is unit elastic. As will be shown later, the choice of \( \phi = 1 \) approximates the value of \( \phi \) that matches the wage inequality implied by the model with observed earnings inequality in the United States. These simplifications allow a concise analysis of how the firm’s hierarchical structure responds to parameter changes. In this simpler setting, the short run solutions in (9) and (10) simplify to

\[
H^* = \theta^* = \left( \beta P \bar{K}^a 2^{\frac{\beta - \rho}{\rho}} \right)^{\frac{1}{\beta - \rho}}. \tag{14}
\]

Similarly, the long run solutions in (11) - (13) simplify to

\[
\theta^{**} = H^{**} = \left[ P \frac{\alpha^a \beta^{1 - a}}{\rho^a} \beta^{\frac{\beta - \rho(1 - \alpha)}{\rho}} \right]^{\frac{1}{\beta(1 - \alpha) - \beta}}, \tag{15}
\]

\[
K^{**} = \left[ P^2 \left( \frac{\alpha}{\rho} \right)^{\frac{\alpha - \beta}{\beta}} \beta^{\frac{\beta(2 - \rho)}{\rho}} \right]^{\frac{1}{\beta(1 - \alpha) - \beta}}. \tag{16}
\]

As can be seen in (14) and (15), the simplification obtained by setting \( \phi = 1 \) introduces symmetry into the firm’s hierarchical structure. It is important to acknowledge the limitation that this imposes on the analysis, for such symmetry is unlikely to hold in reality. Furthermore, setting \( W = 1 \) simplifies the second order conditions considerably. The parsimony that these restrictions allow is such an attractive feature, that we decided to settle for simplicity.

**Lemma 1.** If \( W = \phi = 1 \), second-order conditions for profit-maximization in the short run require \( \beta < 2 \) and \( \rho < 0 \). In the long run, the requirements are \( \alpha < 1 \), \( \beta < 2(1 - \alpha) \) and \( \rho < 0 \).

**Proof:** See the Appendix.

The upper bound of \( \beta \) implied by the long run second order conditions, \( \beta < 2(1 - \alpha) \), implies that the firm operates under decreasing returns to scale. To see this, compare \( \beta < 2(1 - \alpha) \) with \( \alpha + \beta/3 < 1 \) from (7), to obtain \( \beta + 3\alpha < \beta + 2\alpha + 1 < 3 \), which implies diseconomies of scale. This emerges because the wage is a decreasing function of \( h \). Thus, the lowest rank workers are paid progressively less as the firm expands its hierarchy. If workers’ productivity did not fall at a sufficiently high rate as we move down the hierarchy, then a profit-
maximizing firm would expand indefinitely along the vertical dimension. To see the intuition for restricting the substitutability between $H$ and $\theta$ ($\rho < 0$), consider the case when $H$ and $\theta$ are perfectly substitutable ($\rho \to 1$). In this case, the firm can save labour costs by continuously expanding vertically and shrinking horizontally. In summary, $\beta < 2(1-\alpha)$ and $\rho < 0$ ensure a firm of finite size.

The following propositions summarize the short run and long run comparative statics properties of the simplified model:

**Proposition 1.** In the short run, the firm expands vertically and horizontally when output price rises. In the long run, the firm expands vertically and horizontally, and deploys more capital, when output price rises or the rental rate of capital falls.

**Proof:** In the short run, let $Z^* = H^* = \theta^*$. From Lemma 1, we have $\beta < 2$, hence:

$$
P \frac{\partial Z^*}{\partial P} = \frac{1}{2-\beta} > 0.
$$

In the long run, let $Z^{**} = H^{**} = \theta^{**}$. From Lemma 1, we have $\beta < 2(1-\alpha)$, thus:

$$
P \frac{\partial Z^{**}}{\partial P} = \frac{1}{2(1-\alpha)-\beta} > 0, \quad P \frac{\partial K^{**}}{\partial P} = \frac{2}{2(1-\alpha)-\beta} > 0,
$$

$$
r \frac{\partial Z^{**}}{\partial r} = \frac{-\alpha}{2(1-\alpha)-\beta} < 0, \quad r \frac{\partial K^{**}}{\partial r} = \frac{-(2-\beta)}{2(1-\alpha)-\beta} < 0.
$$

As output price rises, marginal revenue rises and becomes greater than marginal cost. The firm takes advantage of this by expanding its hierarchy\(^9\). In doing so, its marginal benefit decreases while its marginal cost increases until they equate again. The result suggests that, in industries in which output prices are protected (e.g., by regulation or trade barriers), firms would be ‘bigger’ in terms of the number of workers they hire. Since $2(1-\alpha)-\beta < 2-\beta$, changes in the hierarchical structure are greater in the long run than in the short run for a given change in $P$. This is a specific instance of the Le Chatelier-Samuelson principle (Samuelson, 1947).

Note also that the output price elasticity of $K^{**}$ is double that of $Z^{**}$. Since the firm’s workforce is equal to $\theta H^2 / 2$ (area of the sector), the price elasticity of the firm’s workforce

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\(^9\) This result is also obtained by Williamson (1967) and Qian (1994), albeit using quite different frameworks.
is triple that of $Z^{**}$. This means that if output price decreases, the firm’s labour force contracts more than its capital stock in percentage terms, leading to an increase in the firm’s capital-labour ratio. This is consistent with the observation that when firms face stronger price competition in a deregulated environment, they typically respond by trimming the workforce and streamlining production.

In the short run the capital stock is fixed, so changes in the rental cost of capital have no effect. However, in the long run, changes in the rental cost of capital affect the hierarchical structure of the firm as well as the capital stock. The long run effects of a rise in the rental cost of capital are of opposite sign to those of a rise in output price.

**Proposition 2.** In the short run, the firm’s hierarchy contracts horizontally and vertically as intra-firm specialization decreases. In the long run, the firm’s hierarchy contracts horizontally and vertically, and uses less capital, as intra-firm specialization decreases.

**Proof:** A decrease in intra-firm specialization is represented by an increase in substitutability between $H$ and $\theta$ (denoted by $\rho$). For the short run, using $\beta < 2$ and $\rho < 0$ (from Lemma 1), we have:

$$\frac{1}{Z^*} \frac{\partial Z^*}{\partial \rho} = \frac{-\beta \ln 2}{\rho^2 (2-\beta)} < 0.$$  

For the long run, using $\beta < 2(1-\alpha)$ and $\rho < 0$ (from Lemma 1), we obtain:

$$\frac{1}{Z^{**}} \frac{\partial Z^{**}}{\partial \rho} = \frac{-\beta \ln 2}{\rho^2 [2(1-\alpha) - \beta]} < 0,$$

$$\frac{1}{K^{**}} \frac{\partial K^{**}}{\partial \rho} = \frac{-2 \beta \ln 2}{\rho^2 [2(1-\alpha) - \beta]} < 0.$$  

By Lemma 1, $\rho$ is negative, hence an increase in $\rho$ causes marginal revenue to decrease. Therefore, the optimal response for the firm is to contract its hierarchy in order to cut costs until marginal cost equates marginal revenue again. The result implies that firms would be smaller (in terms of their labour force) in industries for which division of labour happens to a lesser extent. This is consistent with the observation that a typical manufacturing firm is greater in size than a typical service firm. An extreme example of the latter is the case of tradespersons (‘one-man band’ firms), in which there is no division of labour, and the firm attains the minimum size.
As before, the long run response of the firm’s hierarchical structure is greater than its short run response. In the long run, a reduction in the firm’s workforce is accompanied by a reduction in capital. As with output price, the elasticity of the firm’s workforce with respect to $\rho$ is $3/2$ times that of capital. This means that as intra-firm specialization decreases, the firm’s workforce falls more than capital in percentage terms, leading to an increase in the firm’s capital-labour ratio.

**Proposition 3.** Provided output price is sufficiently high, an increase in returns to scale in the formation of effective labour (that is, a rise in $\beta$) leads to an expansion of the hierarchy in both the short run and long run, and an expansion of capital in the long run. Otherwise, it leads to a contraction of the hierarchy in both the short and the long run, and a contraction of capital in the long run.

**Proof:** In the short run, 
\[
\frac{1}{Z^*} \frac{\partial Z^*}{\partial \beta} = \frac{1}{2(2-\beta)} \left( \frac{1}{\beta} + \frac{1}{\rho} \ln 2 + \ln Z^* \right).
\]
From Lemma 1, recall that $\beta < 2$. If $P$ is sufficiently large (such that $\ln Z^*$ is sufficiently positive), then 
\[
\frac{1}{\beta} + \frac{1}{\rho} \ln 2 + \ln Z^* > 0,
\]
which implies that $\partial Z^*/\partial \beta > 0$.

In the long run, 
\[
\frac{1}{Z^{**}} \frac{\partial Z^{**}}{\partial \beta} = \frac{1}{2(1-\alpha)-\beta} \left( \ln Z^{**} + \frac{1-\alpha}{\beta} + \frac{1}{\rho} \ln 2 \right),
\]
and
\[
\frac{1}{K^{**}} \frac{\partial K^{**}}{\partial \beta} = \frac{1}{2(1-\alpha)-\beta} \left[ \ln K^{**} + \ln r - \ln \alpha + \ln \beta + 1 + (1-\rho) \ln 2/\rho \right].
\]
If $P$ is sufficiently large (such that $\ln Z^{**}$ and $\ln K^{**}$ are sufficiently positive), then 
\[
\ln Z^{**} + \frac{1-\alpha}{\beta} + \frac{1}{\rho} \ln 2 > 0,
\]
and
\[
\ln K^{**} + \ln r - \ln \alpha + \ln \beta + 1 + (1-\rho) \ln 2/\rho > 0.
\]
From Lemma 1, we have $\beta < 2(1-\alpha)$, which together with conditions (17) and (18) implies $\partial Z^{**}/\partial \beta > 0$ and $\partial K^{**}/\partial \beta > 0$.

Conversely, if $P$ is sufficiently low, it follows that $\partial Z^*/\partial \beta < 0$, $\partial Z^{**}/\partial \beta < 0$ and $\partial K^{**}/\partial \beta < 0$. 


A rise in $\beta$ can be interpreted as an improvement in the ‘organizational technology’ of the firm, that is, innovations in the way managers organize workers. Examples of this are changes in the organizational structure of the firm, such as those implied by multidivisional structure (M-form) versus the unitary structure (U-form). Maskin et al. (2000) explain how the unitary form exploits scale/scope economies to a larger extent than the multidivisional form. The results obtained in Proposition 3 imply that changes in returns to scale in the formation of effective labour may not have a uniform effect on all firms. Rather, this will depend on the firm’s environment. In a favourable environment with a high price for output, an organizational innovation leads to firm expansion. Conversely, in an adverse setting, such innovations lead to a contraction of the firm.

6. Wage Inequality within the Firm

In this section, we compute wage inequality with the firm, and show that for certain values of $\phi$, wage inequality will approximate the observed income inequality in the United States during the 1980’s.

Income inequality is typically measured by the Gini coefficient, which involves pairwise comparisons between individual incomes. Since our hierarchical firm features a continuum of workers, pairwise comparisons are not meaningful. Instead, we measure inequality using the Theil indices, which are members of the entropy family (Theil, 1967).

There are two Theil indices of inequality: Theil-L and Theil-T. In the discrete case, the Theil-T measure of wage inequality within the firm is

$$T = \sum_{h=0}^{H} \frac{y(h)}{Y} \ln \left( \frac{y(h) / Y}{l(h) / L} \right)$$

(19)

where $y(h)$ denotes wages earned by workers at hierarchical level $h$, with $y(h) = w(h)h\theta \Delta h$; $Y$ is the total wage bill of the firm, with $Y = \sum_{h=0}^{H} y(h)$; $l(h)$ is the total number of workers between level $h$ and level $h+\Delta h$, with $l(h) = h\theta \Delta h$; and $L$ is the firm’s workforce, with $L = \sum_{h=0}^{H} l(h)$.

For the case when $w(h) = Wh^{-\phi}$ and $\Delta h \to 0$, (19) becomes
Similarly, in the discrete case, the Theil-L measure of wage inequality within the firm is

$$L = \sum_{h=0}^{n} \left( \frac{l(h)}{L} \ln \left( \frac{l(h)/L}{y(h)/Y} \right) \right) \tag{21}$$

When $w(h) = Wh^{-\phi}$ and $\Delta h \to 0$, (21) becomes

$$L = \int_{0}^{n} \left( \ln \left( \frac{2h}{H^2} \right) \frac{2h^\phi}{(2-\phi)H^\phi} \right) dh \tag{22}$$

To ensure that $T$ and $L$ are well defined, $\phi < 2$ (which we assumed previously) is required.

Further analysis yields the following results:

$$\frac{dT}{d\phi} = \frac{\phi}{(2-\phi)^2} > 0 \text{, and } \frac{dL}{d\phi} = \frac{\phi}{2(2-\phi)} > 0.$$ 

Hence wage inequality increases monotonically with the convexity of the wage schedule. The inequality indices, $T$ and $L$, are independent of the specification of the production function, and only rely on the specification of the wage schedule. Thus, wage inequality as measured by the Theil indices is not related to the hierarchical structure of labour, but to the hierarchical structure of wages.

According to figures from the Bureau of Labour Statistics, U.S. Department of Labour, earning inequality as measured by the Theil-T index was between 0.35 and 0.38 during the 1980 to 1988 period (Grubb and Wilson, 1992). For the Theil-T measure of within firm wage inequality to equal 0.38, the required value for $\phi$ is 1.07, which is reasonably close to the benchmark case of $\phi = 1$ examined in section 4 (when $\phi = 1$, $T = 0.31$). Moreover, wage inequality is usually smaller than income inequality, since income inequality includes investment earnings, which are likely to be more significant at the upper end of the income distribution. Although we do not claim that $\phi = 1$ is the appropriate benchmark, the fact that it approximates observed inequality provides some support for the chosen value.
7. Concluding Remarks

This paper introduces a geometric approach to model the hierarchical structure of firms. This approach enables us to incorporate two stylized facts of firms into the neoclassical framework. The first stylized fact is that workers are organized hierarchically in firms, and the second is that wages also exhibit a hierarchical structure. Our framework uncovers some of the underlying forces that shape the firm’s hierarchical structure, whilst taking into account the distribution of wages within the firm.

The geometric approach suggested in the paper differs significantly from other approaches in the literature on the hierarchical structure of firms. Its merit lies in its simplicity. With minor modifications on the standard neoclassical structure, the resulting model sheds light on possible causes of variation in hierarchical structure.

By choosing specific functional forms for the production function and the wage schedule, we obtain explicit short run and long run solutions for the firm’s optimal choice of capital, hierarchical structure, and, as a result, labour. A simplified version of the model has enabled us to examine how the firm’s hierarchical structure changes with output price, intra-firm specialization, and technology (Propositions 1-3).

We have also shown that by choosing a plausible parameterization for the wage schedule, the simplified model can generate an estimate of within-firm wage inequality that approximates the observed earnings inequality in the United States.

The present framework also provides new answers to the questions of the boundaries and size of the firm. The boundaries of the firm are now given by its height and width, and the size of the firm (in terms of its labour force) is now given by the firm’s geometric shape. The underlying forces behind these interpretations are of a similar spirit to Coase’s (1937) original analysis, since the firm’s actions are guided by marginal considerations. However, that is probably where any similarity ends, since the geometric approach itself is an entirely novel framework. Moreover, the boundaries, size and shape of the firm are obtained without any reference to transaction costs. Naturally, this is not to say that the latter are unimportant. Rather, our message is that standard neoclassical forces, in particular returns to scale and diminishing marginal returns, can be used to provide answers to the questions of the boundaries, size, and shape of the firm. Transaction costs would then be an additional force, the introduction of which serves to complement our analysis.

In the general problem outlined in section 2, a position in a firm is defined by two attributes: the seniority of the position, and the activity performed in that position. This study, like Qian (1994) and Williamson (1967), has not considered how activities affect a firm’s
hierarchical structure. For instance, the top manager may prefer to keep strategic activities at arm’s length rather than delegating them to a ‘remote’ department. The role of activity in designing hierarchical structure of firm remains unexplored, and we have only but raised the question. The answers will have to wait for future research.

We close the discussion with a conjecture. Given the closeness of our approach to the standard neoclassical paradigm, it should be possible to insert this model of the firm into a general equilibrium framework. This would bring forth an analysis of the interaction between economy-wide aspects, such as growth, trade and inequality on the one hand and the hierarchical structure of firms on the other. This could be particularly useful in providing an alternative approximation to the question posed by Qian (1994), on the differences between a centrally planned economy featuring a single hierarchy and its capitalist counterpart featuring a multitude of firms. This lies outside the scope of the present paper, and is deferred for future work.

Appendix

Proof of Lemma 1:

In the short run, the firm’s profit simplifies to \( \pi = P\bar{K}^{\alpha} \left( H^\rho + \theta^\rho \right)^{\beta/\rho} - \theta H - r\bar{K} \). For \( H^* \) and \( \theta^* \) to be profit maximizing, the Hessian matrix must be negative semidefinite. The Hessian is given by:

\[
\mathbf{H}^* = \begin{pmatrix}
\pi_{00}^* & \pi_{011}^* \\
\pi_{110}^* & \pi_{111}^*
\end{pmatrix},
\]

where ‘*’ denotes values at the short-run optimum: \( H^* \) and \( \theta^* \), and subscripts denote second order partial derivatives. Sufficient conditions for negative semidefiniteness of \( \mathbf{H}^* \) are as follows: \( \pi_{00}^* < 0, \) \( \pi_{00}^* < 0 \) and \( \pi_{00}^* \pi_{00}^* > (\pi_{111}^*)^2 \). Noting that \( \pi_{111}^* = \pi_{00}^* = (\beta + \rho - 2)/2 \) and \( \pi_{110}^* = \pi_{011}^* = (\beta - \rho - 2)/2 \), the sufficient conditions simplify to \( \beta < 2 \) and \( \rho < 0 \).

In the long-run, the firm’s profit is \( \pi = PK^{\alpha} \left( H^\rho + \theta^\rho \right)^{\beta/\rho} - \theta H - rK \). The associated Hessian is now
\[
\mathbf{H}^{**} = \begin{pmatrix}
\pi^{**}_{HH} & \pi^{**}_{HK} & \pi^{**}_{HK} \\
\pi^{**}_{HK} & \pi^{**}_{KK} & \pi^{**}_{HK} \\
\pi^{**}_{HK} & \pi^{**}_{HH} & \pi^{**}_{KK}
\end{pmatrix},
\]

where ** denotes values at the long-run optimum: \(K^{**}, H^{**}\) and \(\theta^{**}\). Sufficient conditions for negative semidefiniteness of \(\mathbf{H}^{**}\) are: \(\pi^{**}_{i} < 0 (i=K,H,\theta), \pi^{**}_{HH} \pi^{**}_{\theta\theta} > (\pi^{**}_{H\theta})^2, \pi^{**}_{KK} \pi^{**}_{\theta\theta} > (\pi^{**}_{K\theta})^2\) (for \(j=H,\theta\) since \(\pi^{**}_{HH} = \pi^{**}_{\theta\theta}\) and \(\pi^{**}_{HK} = \pi^{**}_{\theta\theta}\)), and \(|\mathbf{H}^{**}| < 0\), where \(|\cdot|\) denotes the determinant. After simplification, sufficient conditions reduce to the following restrictions: \(\alpha < 1, \beta < 2(1-\alpha)\) and \(\rho < 0\).

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